Learning in dynamic simulation games; using performance as a measure

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Abstract

In a dynamic simulation game portraying a multiplier-accelerator investment problem, there are major differences between high and low performers; high performers voice specific concerns for future states of the system, while low performers are less likely to think about the future. Planning, especially incorporating the deceptive nature of feedback, is necessary in systems that exhibit diverging long and short term behaviors. A comparison of game results with written reports shows that there is a positive relationship between performance and understanding of the game. These results are contrary to previous research where performance and understanding have been unrelated (Broadbent et al. 1978, 1986), but can be explained by the added complexity of non-linear feedback tasks with shifts in loop dominance. Such tasks are, in contrast to simple regression model tasks, non-routine and therefore verbal and behavior aspects of decision makers' mental models correspond.

Introduction

Compared to the complexities and uncertainties facing a manager, a airline pilot controls a transparent system. To use a flight simulator analogy, the manager's educational simulation requires that he must learn to perform well in the simulated environment, but more importantly within she must be able to devise appropriate actions in situations different from those simulated. She must be able to re-conceptualize a problem and devise appropriate actions in performance of daily tasks without having access to the simulated environment.

By analyzing player performance in business games, one can gain insight into the process of how managers' assimilate model insights. However, a link between performance and understanding is necessary for such analyses to be fruitful. Previous studies, on the contrary, have documented that performance can be unrelated to understanding (Broadbent et al., 1978; 1986). It is thus necessary to complement performance measures with behavioral data to gain insight in how people make decisions and subsequently learn (Jacoby et al. 1984). If the two types of measures contradict, the task of inferring mental processes can indeed be difficult. --But as long as they correspond, analyzing learning can be done by using several data sources in a triangular fashion; or one can substitute behavior data for performance measures. Such substitution is important, since performance indicators often are more readily available than behavioral data.
This research reports on an experiment where we contrast performance and behaviorally derived data in a quasi-continuous feedback game. Decision making in the game has been extensively reported elsewhere (Sterman 1987; 1989). Low transparency leads to poor performance and faulty decision making; which in turn can be explained by players' initial misperceptions of supply line feedback (Sterman 1989).

In addition to attempting to find a relationship between performance and other indicators of understanding, this paper also provides a corroboration of the heuristics proposed by earlier work on statistical estimation of decision rules in this game (Sterman 1986; 1989). We first briefly review relevant literature on learning in static and various feedback tasks. Then the experiment is described and its results pointed out. Finally, a discussion of the findings is carried out.

**Previous work**

Dynamic tasks are harder to research than static ones; they take longer to study, may require sophisticated mathematics to solve for optimality and often demand (what used to be very) expensive computer set-ups (Slovic et al. 1977). Led by Tversky and Kahnemann (1981) the main finding in static decision making tasks has been that people make inappropriate decisions and act inconsistently. The underlying explanation is, in common language, that in order to survive in an everyday environment that would be chaotic if people should calculate optimal solutions, people perform according to simple rules of thumb. These simplifying heuristics can however perform well in real world environments (Klayman and Young-Won 1987), but in experimental situations without feedback decision makers can make faulty inferences (Hogarth 1981).

In particular, most real life situations are so constructed that cue redundancy and feedback will help an non-reflective decision maker. Even if he follows simple rules of thumb, he might perform quite well, but often he doesn't; the problematic dimensions of situations when people perform poorly are not well understood (Hogarth 1981). Some issues have been dealt with, however; in outcome feedback situations; i.e. in tasks where subjects must infer the true relationships between two variables in presence of several, often distorted cues, it has been shown that non-linear relationships are hard to infer (Brehmer 1978). Beyond a certain noise factor, subjects are unable to make correct inferences.

However, real life tasks are in general not inference tasks, they require action; when a person makes a decision, he also acts and receives consequential feedback from the task. Hogarth (1981) has proposed that existence of continuous tasks can explain why people use heuristics requiring little cognitive effort; it may pay off to make many decisions and adjust according to feedback instead of relying heavily on "one shot" decisions involving complex information processing. Hogarth's view is consonant with Simon's (1981) point that cognitive processing need not be very complex; decision making environments are often so construed that the rules can be very simple, yet the outcome can be satisfactorily. Concerned with a medical task with abundantly available information, Kleinmuntz and Thomas (1987) show that there exist cognitive effort/accuracy payoffs. In their task subjects rely too much on inference when use of simple heuristics, action and feedback would have yielded higher performance.
Similarly, when individuals have available only action feedback, they misperceive the nature of simple structural relationships (Sterman 1986, 1989). But more importantly, subjects tend to pay attention to salient features of the task and not to subtle aspects. In particular, Sterman shows that by paying due attention to supply lines, performance can be improved.

Brehmer (1987, 1988) has investigated a similar simulated decision making task. Instead of Sterman's statistically estimated decision rules, he uses other protocols to discuss differences in performance. Of particular interest is his finding that high performing players use planning (or feedforward as he puts it) to infer future states of the system. In a task where conditions change exponentially, such as the forest firefighting he looks at, this ability is crucial; without planning a couple of time periods ahead, subjects never get their firefighters to the fire on time and keep sending fire engines to already blackburned areas.

Broadbent et al. (1986) show that there is not necessarily a link from performance to understanding; verbalizable knowledge is not used in game playing since high performers give wrong answers to questions and vice versa. Their work posits that decisions are largely subconscious, and that conscious verbalizations are not connected to actual decision making in the simple inference tasks. However, if the task is sufficiently unfamiliar, as the one we have chosen, decision making and verbalization should correspond; according to Rasmussen (1976) and Ericsson and Simon (1984), verbalizations will reflect underlying inference processes if a task departs sufficiently from routine. Although Broadbent et al.'s subjects where unfamiliar with the management task they dealt with, its linear nature led them to make a simple linear extrapolation; a meta-task they must have been familiar with. It therefore resembled a routine task and is not amenable to protocol analysis and questionnaires.

The experimental task

The task discussed below is imbedded in a game (Sterman 1986) and the structure is related to a phenomenon called the economic long wave and illustrates how capital self-ordering can cause fluctuations in economic activities. In the game individuals are in charge of the capital ordering decision for a simulated company. The tricky issue in the model arises from the firm's need for its own capital to produce finished goods, and that for a period of time increased capacity can only be obtained by restricting deliveries to final customers. Initially this self-reinforcing feedback loop is hard to detect, thus overcapacity builds up and cycles with some 50 year's period develop.

One trial consists of 36 decisions with a given sequence of exogenous final consumer demand. There were 4 different demand patterns; (1) one time step of 10 %; (2) linear growth; (3) sinusoidal pattern and (4) stable with a random component. The first demand pattern is called basic and the others are labeled as advanced. All players played the basic game at least once, and most of them played it several times. Approximately 1/3 were asked to use each of the advanced demand patterns. Performance was worse in the advanced game; which reflects the
higher optimal score of these games (3-4 times the basic game's optimal score of 19) as well as the added cognitive complexity inherent in forecasting future states in the advanced games.

In the results reported here, we used a subject pool of 50 MIT students enrolled in two different introductory System Dynamics classes. Most of them (80%) were graduate students and the others were undergraduate students. The task was a homework assignment and explicitly graded on consistency (and not performance). The grade on this task counted for about 10% of the term grade and the students had about two weeks to finish the assignment. The game was their second computer game of the term, so they were familiar with tasks wherein "Boom-and-bust" phenomena could occur. Since previous results (Bakken 1988) show no significant difference in the same game if performed by System Dynamics novices or introductory students, we assume that the findings are generalizable to other decision makers.

Method and results

In the first basic game trial, the optimum score was 19¹ and the median score in experiments with groups of 10 to 50 subjects have varied between 230 and 560. Thus, we (arbitrarily) defined a high performer as one having an average score of less than 150 in his 2 first basic games and a low performer as someone having more than 500 average score in the same games. Since most of the 50 players received scores between the two extremes, and some players only played the first game once, only 17 players were selected for inclusion into our two groups; 6 in the low performer category and 11 in the high performer.² Below, in tables 1 and 2, performance in the games is shown. Note that high performers do better than low performers also in the advanced games.

<table>
<thead>
<tr>
<th></th>
<th>First two basic games</th>
<th>[First basic game Second basic game]</th>
<th>First advanced game</th>
</tr>
</thead>
<tbody>
<tr>
<td>Average High performer (n=11)</td>
<td>106 (44)</td>
<td>[116 (47) 97 (43)]</td>
<td>649 (682)</td>
</tr>
<tr>
<td>Average Low performers (n=6)</td>
<td>861 (619)</td>
<td>[1090 (725) 633 (439)]</td>
<td>984 (654)</td>
</tr>
</tbody>
</table>

¹There was no relationship between the number of additional games played after the first two basic ones and subsequent advanced scores.

²The low performers played 4.33 (.74) basic games on average, whereas the high performers played 3.54 (1.23), but we only report the two first ones. [Numbers in parenthesis are standard deviations]
Table 1: Scores for high and low performers; standard deviations in parentheses.

<table>
<thead>
<tr>
<th>Input</th>
<th>High performers (n=5)</th>
<th>Low performers (n=1)</th>
<th>Average advanced trial</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sine advanced</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>111</td>
<td>1265</td>
<td>229</td>
</tr>
<tr>
<td>Noise advanced</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>84</td>
<td>819</td>
<td>232</td>
</tr>
<tr>
<td>Ramp advanced</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>8</td>
<td>626</td>
<td>1866</td>
</tr>
</tbody>
</table>

Table 2: Distribution of scores according to performance category and nature of advanced game input.

In order to make investigate determinants of high performance, data files were scrutinized to find whether equilibrium was reached the basic trials. Whereas none of the low performers reached equilibrium, 5 and 4 of the high performance players reached equilibrium in game 1 and 2 respectively. Likewise, written reports handed in by the students were subjected to content analysis for the mentioning of a) an equilibrium state to reach and b) self-reinforcing feedback; both crucial aspects in understanding the system’s behavior. The results are shown below; 63 % of the high performers mention both factors whereas only 17 % of the low performing students do.

<table>
<thead>
<tr>
<th>Performance Category</th>
<th>Equilibrium reached</th>
<th>Eq. mentioned</th>
<th>Self-reinforcing feedback mentioned</th>
<th>Both mentioned</th>
</tr>
</thead>
<tbody>
<tr>
<td>High performers</td>
<td>.50</td>
<td>.40</td>
<td>.100</td>
<td>.63</td>
</tr>
<tr>
<td>Low performers</td>
<td>.00</td>
<td>.00</td>
<td>.33</td>
<td>.67</td>
</tr>
</tbody>
</table>

Table 3: Measures of understanding of the system taken from result file data and from content analysis of written reports (number of hits/number of players).

In sum, there is a positive relation between behavior and performance data between behavior and performance data. This is due to the opaqueness of the model as evidenced by its delay structure and self-reinforcing relationships and players must develop understanding and heuristics in the game in the game proper. In contrast, Broadbent et al.'s task (1978) was of another nature, so that regression extrapolation was appropriate. The difference between a linear regression equation and a non-linear system where loop dominance shifts from positive to negative is the main reason why we find correspondence between behavioral and performance data here but not in Broadbent’s work.

The nature of behavior measures in both this game and previous findings is important in order to understand the performance in the game beyond the mere recognition that performance and behavior corresponds. How and why is behavior as it is in this system?

Discussion of behavior data

A phenomenological account of poor performance in a related task is provided by Dömer (1980). Treating the issue of decision making strategies in a town planning environment, he finds that low performers do poorly
mainly because they are "thematic vagabonds". Instead of comprehensive testing of a single hypothesis, they abandon it before the hypothesis can be validated. Frequent shifts in strategies are counter-productive in situations with substantial delays, such as town planning. The investment task studied here is similar, in the sense that ordered capital does not become available at once.

Without holding on to one policy; i.e. high or low capital ordering, the appropriate strategy might never be found. The best policy this game is to take the unpleasant medicine (ordering much; thus having initial discrepancies between desired and actual outputs) early. If such a bold step is not taken, then the firm's symptoms (growing backlog of orders) become successively worse and the medicine that would previously have cured the system (a shock order of 200) will not be strong enough. In fact, the dose must be increased 10-fold if the conditions are allowed to develop without appropriate intervention early on; taking what would have been an appropriate dose initially will, at a later stage only make matters worse.

Is there also any evidence of difference between high and low performers in transfer of performance? The answer is yes; all high performers do better than low performers in the advanced game. As one would expect, however, the difference is more marked for the noise and the sine condition. These two external inputs reflect stationary processes with no more than 20% deviations from the initial equilibrium. Heuristics developed from the first basic trials, where a key issue is to calculate an expected equilibrium condition, does quite well; subjects' general heuristic of not paying attention to excursions from equilibrium, limiting orders and stay in a surplus capacity situation do well. In contrast, such heuristics are devastating when the input is a ramp. By not paying sufficient attention to the discrepancies between actual and desired quantities, their backlog grow out of bounds and poor performance results.

The high performers indeed show many other signs that they do understand the system. 63% of them specifically mention that positive feedback and voice concern for future equilibrium conditions, whereas only 17% of the low performers do the same. Their strategies are also different from the low performers; instead of "trying to get production capacity up to desired production" (a common statement among low performers) they voice a concern for what the future equilibrium of the system will be. Thus they develop detectors for excursions from the equilibrium and succeed in avoiding them and can explain why only mentioning positive feedback, as do 67% of the low performers, is inadequate for high performance.

But why is it that low performers do so poorly, in particular, how is it that they fail to take the supply line into account (Sterman 1989). The high performers, since they calculate equilibrium and understand the positive feedback complexity pay less attention to the actual numbers on the screen; they pay less attention to actual feedback and instead use their own mental simulation of what the state of the system will be some periods ahead. Previous findings of high performers lack of attention to feedback (Jacoby et al., 1984) suggest that due to self-reliance and mental simulating capacity they anticipate irregularities in the feedback and therefore pay little attention to it. In a slightly different task, Hammond et al. (1973) has shown that if a cue is noisy, players are better off not paying attention to outcome feedback.
Our experiment deals with a strong positive feedback instead of noise, but the same phenomenon occurs. By anchoring on the underlying structure of the system and not just on its behavioral manifestations high performers are able to discount the transient behavior of the system and devise appropriate capital ordering. In fact, by specifically addressing the particularities of this system and by developing appropriate heuristics, they are also able to transfer to new situations much better than the low performers.

By observing one player in detail, we have corroborated the distinction between high and low performers. Using concurrent verbal protocols (Ericsson and Simon 1984), we had access to her information processing. This player went from "low" to "high" performance during the first two trials, so she is not part of either group previously discussed. In the first trial, she does not develop any concept of equilibrium. She feels very frustrated by the fact that by ordering more capital she simultaneously creates additional unfilled demand. Her initial inference, validated by early decisions and feedback, is that it pays be be cautious; "careful ordering is better". Although she detects the positive feedback loop in her second basic trial and the equilibrium state in her third, the initial strategy of "don't be aggressive" remains a strong behavioral anchor. In her first advanced trial, she thus performs miserably with a ramp input. Her conservative strategy, only slightly dysfunctional in her basic trials, yields disastrous results when she must accommodate a ramp input. It takes her three advanced trials to learn that an aggressive strategy is called for. In other words, there is more to good performance and transfer of insight than just a recognition of self-reinforcing feedback and equilibrium.

Future work will have to address those dimensions of transfer; here we have merely established the positive relation between several indicators of understanding and performance itself.

Implications for managerial and research practice

The main lesson from this research is that performance is a reasonable indicator of dynamic understanding. One can thus measure performance in a game with positive feedback, delays and non-linearities and conclude that high performers have figured out key structural properties of the system, and that they can translate that understanding into appropriate decisions. Management consultants and researchers who use games of complex, dynamic systems as tools to transfer systems insights can therefore safely use performance measures as first approximations of structural understanding.

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